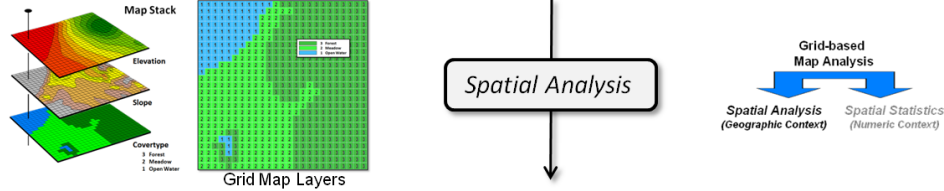


# Spatial Analysis Operations *(Geographic Context)*

GIS as “Technological Tool” (*Where is What*) vs. “Analytical Tool” (*Why, So What and What if*)



## GIS Perspective:

**Reclassify** (*Position, Value, Size, Shape, Contiguity*)

**Overlay** (*Location-specific, Region-wide*)

**Distance** (*Distance, Proximity, Movement, Optimal Path, Visual Exposure*)

**Neighbors** (*Characterizing Surface Configuration, Summarizing Values*)

Map Analysis Toolbox



## Mathematical Perspective:

**Basic GridMath & Map Algebra** (+ - \* /)

**Advanced GridMath** (*Math, Trig, Logical Functions*)

**Map Calculus** (*Spatial Derivative, Spatial Integral*)

**Map Geometry** (*Euclidian Proximity, Narrowness, Effective Proximity*)

**Plane Geometry Connectivity** (*Optimal Path, Optimal Path Density*)

**Solid Geometry Connectivity** (*Viewshed, Visual Exposure*)

✓ **Unique Map Analytics** (*Contiguity, Size/Shape/Integrity, Masking, Profile*)

## Spatial Analysis Operations — Mathematical Perspective

*...of Raster-based Map Analysis and Modeling Operations*

*...for Esri **Spatial Analyst Software***

Mathematical Concepts	Spatial Analyst Tool	Comments
<b>Basic GridMath &amp; Map Algebra</b> (+ - * /):		
	<b><u>General Math Toolset, Basic Arithmetic tools:</u></b> Plus, Minus, Times, Divide Power	Adds (sum), subtracts, multiplies, and divides the values of two input grids on a cell-by-cell basis, raises the cell values in one input grid to the power of the values found in another.
	<b><u>General Math Toolset, Power tools:</u></b> Square, Square Root	Calculates the square and the square root of an input grid.
	<b><u>Map Algebra Toolset:</u></b> Raster Calculator	Builds and executes a single Map Algebra expression using Python syntax in a calculator-like interface.
<b>Advanced GridMath</b> ( <i>Math, Trig, Logical Functions</i> ):		
	<b><u>General Math Toolset, Conversion tools:</u></b>	Calculates the absolute value, changes the sign (multiplies by -1), converts each cell

	<p><b>Abs, Negate, Float, Int, Round Down, Round Up; Mod</b></p>	<p>value to floating-point, to integer, to next lower whole number, and to next higher whole number on a cell-by-cell basis of an input grid; <b>Mod</b> finds the remainder (modulo) of the first input grid when divided by the second grid on a cell-by-cell basis.</p>
	<p><b><u>General Math Toolset, Exponential and Logarithmic tools:</u></b>  <b>Exp, Exp2, Exp10, Ln, Log2, Log10</b></p>	<p>Calculates the base<sub>e</sub> exponential, base<sub>10</sub> exponential, base<sub>2</sub> exponential, natural logarithm (base<sub>e</sub>), base<sub>10</sub> logarithm, base<sub>2</sub> logarithm of an input grid.</p>
	<p><b><u>Trigonometric Math Toolset:</u></b>  <b>Cos, Sin, Tan, ACos, ASin, ATan, ATan2, CosH, SinH, TanH, ACosH, ASinH, ATanH,</b></p>	<p>Calculates the cosine, sine, tangent, inverse cosine, inverse sine, inverse tangent, inverse tangent (based on y/x), hyperbolic sine, hyperbolic cosine, hyperbolic tangent, Inverse hyperbolic sine, inverse hyperbolic cosine, inverse hyperbolic tangent of an input grid.</p>
	<p><b><u>Logical Math Toolset, Relational tools:</u></b>  <b>Equal To, Not Equal, Greater Than, Greater Than Equal, Less Than, Less Than Equal</b></p>	<p>Performs a Relational equal-to, not-equal-to, greater-than, greater-than-or-equal-to, less-than, less-than-or-equal-to on two input grids on a cell-by-cell basis.</p>
	<p><b><u>Logical Math Toolset, Boolean tools:</u></b>  <b>Boolean And, Boolean Or, Boolean Xor; Boolean Not</b></p>	<p>Performs a AND, OR Boolean exclusive-OR on two input grids; <b>Boolean Not</b> performs Boolean complement on the values of a single input grid.</p>
	<p><b><u>Logical Math Toolset, Combinatorial tools:</u></b>  <b>Combinatorial And, Combinatorial Or, Combinatorial XOR</b></p>	<p>Performs a Combinatorial AND, OR, exclusive-OR operation on two input grids.</p>
	<p><b><u>Logical Math Toolset, Logical tools:</u></b>  <b>Diff, InList, Is Null, Over, Test</b></p>	<p><b>Diff</b> determines which values from the first input are logically different from the values of the second input.  <b>In List</b> determines which values from the first input are contained in the &lt;argument_list&gt;.  <b>Is Null</b> Determines which values from the input grid are NoData on a cell-by-cell basis.  <b>Over</b> returns those values from the first input that are nonzero; otherwise, returns the value from the second input.  <b>Test</b> Performs a Boolean evaluation of the input raster using a logical expression.</p>
	<p><b><u>Conditional Toolset:</u></b>  <b>Con</b></p>	<p><b>Con</b> performs a conditional if/else evaluation on each of the input cells of an input raster.</p>
	<p><b><u>Bitwise Toolset:</u></b>  <b>Bitwise XOr, And, Or; Bitwise Not</b></p>	<p>Performs a Bitwise exclusive-OR, AND, OR on the binary values on two input grids; <b>Bitwise Not</b> performs a Bitwise complement on the binary value of an input grid.</p>
<p><b>Map Calculus</b> (<i>Spatial Derivative, Spatial Integral</i>):</p>		
	<p><b><u>Surface Toolset, Surface Configuration tools:</u></b>  <b>Slope, Aspect, Curvature</b>  <i>Spatial Derivative</i></p>	<p><b>Slope</b> identifies the rate of maximum change in z value from each cell (derivative).  <b>Aspect</b> identifies the direction of maximum rate of change in z value from each cell (direction of the derivative).</p>

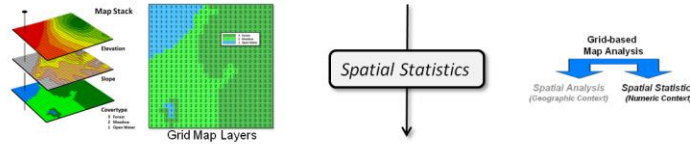
	(single continuous surfaceMap grid)	<b>Curvature</b> calculates the curvature of a surface at each cell center (surface curvature of the derivative).
	<b>Zonal Toolset, Zonal Statistics tools:</b> <b>Zonal Statistics</b> <i>Spatial Integral</i> (discrete <zone_grid> as a template and continuous <value_grid> as data layers)	<b>Zonal Statistics</b> calculate statistics on values in a grid (<value_grid>) within the zones of another grid (<zone_grid>) to include <i>Sum, Mean, STD, Median, Minimum, Maximum, Range, Majority</i> (most often; mode), <i>Minority</i> (least often), and <i>Variety</i> (diversity).
<b>Map Geometry</b> (Euclidian Proximity, Effective Proximity):		
	<b>Distance Toolset, Euclidean Distance tools:</b> <b>Euclidean Distance, Euclidean Direction, Euclidean Allocation</b> <i>Euclidean distance is defined as the shortest straight line between two locations</i> (single map layer for simple Euclidean distance)	<b>Euclidean Distance</b> calculates for each cell the Euclidean distance to the closest "source" location. <b>Euclidean Allocation</b> assigns the map value of the closest "source cell" (in Euclidean distance) for every grid location. <b>Euclidean Direction</b> calculates, for each cell, the direction, in degrees, to the nearest "source" location.
	<b>Distance Toolset, Effective Distance tools:</b> <b>Cost Distance, Cost Allocation, Cost Back Link</b> <i>Effective distance is defined as the not necessarily straight route connecting two locations considering intervening relative and absolute barriers to movement</i> (Friction map layer required for effective "cost" distance)	<b>Cost Distance</b> calculates for each cell the least-accumulative-cost distance over a cost surface to a "source" cell or a set of source cells as the least accumulative cost over a cost surface. <b>Cost Allocation</b> assigns the map value of the closest "source cell" (in Effective distance) for every grid location as the least accumulative cost over a cost surface. <b>Cost Back Link</b> defines the neighbor that is the next cell on the least-accumulative-cost path from a cell to a set of source cells.
<b>Plane Geometry Connectivity</b> (Optimal Path, Optimal Path Density, Surface Configuration):		
	<b>Distance Toolset, Effective Distance tools</b> (path connectivity): <b>Cost Path, Path Distance, Corridor, Path Distance Allocation, Path Distance Back Link</b> (SurfaceMap and sourceMap)	<b>Cost Path</b> calculates the least-cost path from a source to a destination over a surface grid. Least Cost Path (optimal Path) analysis produces an output grid that records the least-cost path(s) from selected cell(s) in the input <fromcell_grid>, or from interactive selection on the display, to the closest source cell defined within the <accumcost_grid> in terms of cost distance. <b>Path Distance</b> calculates, for each cell, the least accumulative cost distance to the nearest source, while accounting for surface distance and horizontal and vertical cost factors. <b>Corridor</b> records for each cell location the sum of the accumulative costs for two input accumulative-cost grids. <b>Path Distance Allocation</b> Calculates the nearest source for each cell based on the least accumulative cost over a cost surface, while accounting for surface distance and horizontal and vertical cost factors. <b>Path Distance Back Link</b> Defines the neighbor that is the next cell on the least accumulative cost path to the nearest

		source, while accounting for surface distance and horizontal and vertical cost factors.
	<b><u>Hydrology Toolset, Flow Density tools:</u></b> <b>Flow Accumulation</b> <i>(SurfaceMap and sourceMap)</i>	<b>Flow Accumulation</b> creates a grid of accumulated flow to each cell, by accumulating the weight for all cells that flow into each downslope cell.
	<b><u>Hydrology Toolset, Surface Configuration tools:</u></b> <b>Flow Length, Flow Direction, Sink, Fill, Watershed, Basin, Focal Flow</b> <i>(SurfaceMap)</i>	<b>Flow Length</b> calculates the upstream or downstream distance, or weighted distance, along the flow path for each cell. <b>Flow Direction</b> creates a grid of flow direction from each cell to its steepest downslope neighbor. <b>Sink</b> Fills sinks in a surface raster to remove small imperfections in the data. <b>Fill</b> fills sinks or levels peaks in a continuous grid to remove small imperfections in the data. <b>Watershed</b> determines the contributing area above a set of cells in a grid. <b>Basin</b> creates a grid delineating all drainage basins within the analysis window. <b>Focal Flow</b> determines the flow of the values in the input raster within each cell's immediate neighborhood.
<b>Solid Geometry Connectivity</b> <i>(Visual Exposure):</i>		
	<b><u>Surface Toolset, Visual Connectivity tools:</u></b> <b>Viewshed, Observer Points</b> <i>(surfaceMap and sourceMap layers)</i>	<b>Viewshed</b> determines the grid surface locations visible to a set of observer features. <b>Observer Points</b> identifies which observer points (up to 16 locations) are visible from each raster surface location.
<b>Unique Map Analytics</b> <i>(Reclassify, Contiguity, Shape):</i>		
	<b><u>Reclass Toolset, Reclassification tools:</u></b> <b>Reclass, Slice</b> <i>(continuous or discrete map layers)</i>	<b>Reclass</b> reclassifies (or changes) individual or ranges of values in a grid interactively or by using a <i>remap table</i> or <i>ASCII file</i> . <b>Slice</b> reclassifies ('slices' or changes) the range of values of the input cells into zones of equal interval, equal area, or by natural breaks.
	<b><u>Local Toolset, Combinatorial tool:</u></b> <b>Combine</b> <i>(discrete map layers)</i>	<b>Combine</b> combines multiple grids (up to 20) on a cell-by-cell basis, such that a unique output value is assigned to each unique combination of input values.
	<b><u>Generalization toolset, Contiguity tool:</u></b> <b>Region Group, Nibble, Majority Filter</b> <i>(discrete map layer)</i>	<b>Region Group</b> assigns to each cell in the output grid, the identity of the connected region to which that cell belongs. A unique number is assigned to each region. <b>Nibble</b> replaces cells of a raster corresponding to a mask with the values of the nearest neighbors. <b>Majority Filter</b> replaces cells in a raster based on the majority of their contiguous neighboring cells.
	<b><u>Surface Toolset, Surface Configuration</u></b>	<b>Cut Fill</b> calculates the volume change between two surfaces. This is typically used

	<p><b>tool:</b>  <b>Cut Fill</b>  <i>(two SurfaceMaps)</i></p>	<p>for cut and fill operations.</p>
	<p><b><u>Zonal Toolset</u>, Zonal Geometry:</b>  <b>Zonal Geometry</b>  <i>(discrete templateMap and continuous dataMap layers)</i></p>	<p><b>Zonal Geometry</b> calculates for each zone in a dataset the specified geometry measure to include <i>Area</i>, <i>Perimeter</i>, <i>Centroid</i> (identifies the geometric center of each zone), and <i>Thickness</i> (calculates the deepest or thickest point within each zone from its surrounding cells).</p> <p>Several tools for tabular summary, extracting and other processing are available to include <i>Tabulate Area</i>, <i>Zonal Fill</i>, <i>Zonal Geometry</i>, <i>Zonal Geometry as Table</i> and <i>Zonal Statistics as Table</i>.</p>

## Spatial Statistics Operations *(Numeric Context)*

GIS as “Technological Tool” (Where is What) vs. “Analytical Tool” (Why, So What and What if)



### GIS Perspective:

**Surface Modeling** (Density Analysis, Spatial Interpolation, Map Generalization)

**Spatial Data Mining** (Descriptive, Predictive, Prescriptive)

Map Analysis Toolbox



### Statistical Perspective:

**Basic Descriptive Statistics** (Min, Max, Median, Mean, StDev, etc.)

**Basic Classification** (Reclassify, Binary/Ranking/Rating Suitability)

**Map Comparison** (Joint Coincidence, Statistical Tests)

✓ **Unique Map Descriptive Statistics** (Roving Window Summaries)

✓ **Surface Modeling** (Density Analysis, Spatial Interpolation)

**Advanced Classification** (Map Similarity, Maximum Likelihood, Clustering)

**Predictive Statistics** (Map Correlation/Regression, Data Mining Engines)

## Spatial Statistics Operations — Statistical Perspective

...of Raster-based Map Analysis and Modeling Operations

...for Esri **Spatial Analyst Software**

Statistical Concepts	Spatial Analyst Tool	Comments
<b>Basic Descriptive Statistics</b> (Min, Max, Median, Mean, StDev, etc.):		
	<b>Local Toolset, Cell Statistics tools:</b> <b>Cell Statistics</b> (two or more grid layers)	<b>Cell Statistics</b> calculates a per-cell statistic from multiple input grids to include— <b>MEAN, MEDIAN, MINIMUM, MAXIMUM, MAJORITY, MINORITY, RANGE, STD, SUM, VARIETY</b> of values on a cell-by-cell basis.
	<b>Local Toolset, Frequency tools:</b> <b>Equal To Frequency, Greater Than Frequency, Less than Frequency</b> (evaluation grid; followed by two or more grid layers)	<b>Equal To Frequency</b> evaluates on a cell-by-cell basis the number of times the values in a set of grid layers are equal to the values in an evaluation grid. <b>Greater Than Frequency</b> evaluates on a cell-by-cell basis the number of times the values in a set of grid layers are greater than the values in an evaluation grid.. <b>Less than Frequency</b> evaluates on a cell-by-cell basis the number of times the values in a set of grid layers are less than the values in an evaluation grid..
	<b>Local Toolset, Ranking tools:</b> <b>Rank, Lowest Position, Highest Position, Popularity</b> (two or more grid layers)	<b>Rank</b> values from the set of input grids are ranked on a cell-by-cell basis, and which of these gets returned is determined by the value of the rank input grid (e.g., 1 = first rank position, 2= second position, etc.). <b>Lowest Position</b> determines on a cell-by-

		<p>cell basis the position of the grid layer with the minimum value in a set of grids (grid stack).</p> <p><b>Highest Position</b> determines on a cell-by-cell basis the position of the grid layer with the maximum value in a set of grids (grid stack).</p> <p><b>Popularity</b> determines the value in an argument list that is at a certain level of popularity on a cell-by-cell basis. The particular level of popularity (the number of occurrences of each value) is specified by the first argument.</p>
	<p><b><u>Overlay Toolset:</u></b>  <b>Weighted Overlay, Weighted Sum,</b>  <i>(two or more grid layers)</i></p>	<p><b>Weighted Overlay</b> overlays several grid layers using a common measurement scale and weights each according to its importance. The cell values are multiplied by their percentage influence, and the results are added together to create the output raster.</p> <p><b>Weighted Sum</b> overlays several grid layers, multiplying each by their given weight and summing them together.</p>
<p><b>Basic Classification</b> (<i>Reclassify, Contour, Normalization</i>):</p>		
	<p><b><u>Reclass Toolset, Reclassification tools:</u></b>  <b>Reclass, Slice</b>  <i>(continuous or discrete map layers)</i></p>	<p><b>Reclass</b> reclassifies (or changes) individual or ranges of values in a grid interactively or by using a remap table.</p> <p><b>Slice</b> reclassifies ('slices' or changes) the range of values of the input cells into zones of equal interval, equal area, or by natural breaks.</p>
	<p><b><u>General Math Toolset, Basic Arithmetic tools:</u></b>  <b>Plus, Minus, Times, Divide Power</b></p>	<p>Normalize a map layer using standard normalization equations such as percent of a specified Goal, specified value Range, or Standard Normal Variable—</p> <ul style="list-style-type: none"> <li>– <math>Norm\_Goal = (mapValue / Goal\_value) * 100</math></li> <li>– <math>Norm\_Range = ((mapValue - mapMin) * rangeMax) / (mapMax - mapMin) + rangeMin</math></li> <li>– <math>Norm\_SNV = ((mapValue - mean) / StDev) * 100</math></li> </ul> <p>where mapValue is the map layer variable to be normalized and all other terms are constant values.</p>
<p><b>Map Comparison</b> (<i>Joint Coincidence, Difference</i>):</p>		
	<p><b><u>Local Toolset, Combinatorial tool:</u></b>  <b>Combine</b>  <i>(discrete map layers)</i></p>	<p><b>Combine</b> combines multiple grids (up to 20) on a cell-by-cell basis, such that a unique output value is assigned to each unique combination of input values.</p>
	<p><b><u>General Math Toolset, Basic Arithmetic tools:</u></b>  <b>Plus, Minus, Times, Divide Power</b></p>	<p>Subtract two grid layers for a "difference grid"; divide the difference grid by one of the grids for a "difference ratio" grid; multiply the difference ratio grid times 100 for a "percent difference" grid.</p>
<p><b>Unique Map Statistics</b> (<i>Zonal, Roving Window and Block Summaries</i>):</p>		

	<p><b><u>Zonal Toolset, Zonal Statistics tools:</u></b>  <b>Zonal Statistics</b>  <i>Spatial Integral</i>  <i>(discrete &lt;zone_grid&gt; as a template and continuous &lt;value_grid&gt; as data layers)</i></p>	<p><b>Zonal Statistics</b> calculate statistics on values in a grid (&lt;value_grid&gt;) within the zones of another grid (&lt;zone_grid&gt;) to include <i>Sum, Mean, STD, Median, Minimum, Maximum, Range, Majority</i> (most often; mode), <i>Minority</i> (least often), and <i>Variety</i> (diversity).</p>
	<p><b><u>Neighborhood Toolset, Focal (roving window) tools:</u></b>  <b>Focal Statistics, Filter</b>  <i>(single continuous grid layer)</i></p>	<p><b>Focal Statistics</b> calculates for each input cell location a statistic of the values within a specified neighborhood around it to include—  <b>SUM, MEAN, STD, MEDIAN, MINIMUM, MAXIMUM, RANGE, MAJORITY</b>, (most often; mode), <b>MINORITY</b> (least often), <b>VARIETY</b> (diversity). The value is assigned to the center (focus) cell of the roving window.  <b>Filter</b> performs either a smoothing (Low pass) or edge-enhancing (High pass) filter on a raster.</p>
	<p><b><u>Neighborhood Toolset, Block tool:</u></b>  <b>Block Statistics</b>  <i>(single continuous grid layer)</i></p>	<p><b>Block Statistics</b> partitions the input grid into non-overlapping blocks and calculates the statistic of the values within each block—  <b>SUM, MEAN, STD, MEDIAN, MINIMUM, MAXIMUM, RANGE, MAJORITY</b>, (most often; mode), <b>MINORITY</b> (least often), <b>VARIETY</b> (diversity). The value is assigned to all of the cells in each block in the output in a manner similar to Zonal tools.</p>
	<p><b><u>Raster Creation Toolset:</u></b>  <b>Create Constant Raster, Create Normal Raster, Create Random Raster</b></p>	<p><b>Create Constant Raster</b> creates a grid layer (raster) of a constant value within the extent and cell size of the analysis window.  <b>Create Normal Raster</b> creates a grid layer (raster) of random values with a normal (gaussian) distribution within the extent and cell size of the analysis window.  <b>Create Random Raster</b> creates a grid layer (raster) of random floating point values between 0.0 and 1.0 within the extent and cell size of the analysis window.</p>
<p><b>Surface Modeling</b> (<i>Density Analysis, Spatial Interpolation</i>):</p>		
	<p><b><u>Neighborhood Toolset, Focal (roving window) tool:</u></b>  <b>Focal Statistics (sum)</b>  <i>(single grid layer with point sample values)</i></p>	<p><b>Focal Sum</b> for each cell location on an input grid adds the point values within a specified neighborhood to create a density map of the total number of occurrences within a specified reach of each grid location.</p>
	<p><b><u>Interpolation Toolset:</u></b>  <b>IDW, Kriging, Spline, Spline with Barriers, Natural Neighbor, Trend</b>  <i>(single grid layer with point sample values)</i></p>	<p><b>IDW</b> interpolates a continuous grid surface from points using an inverse distance weighted (IDW) technique.  <b>Kriging</b> interpolates a continuous grid surface from points using kriging.  <b>Spline</b> interpolates a continuous grid surface from points using a two-dimensional minimum curvature spline technique.  <b>Spline with Barriers</b> interpolates a raster surface, using barriers, from points using a</p>



		<p>minimum curvature spline technique. The barriers are entered as either polygon or polyline features.</p> <p><b>Natural Neighbor</b> interpolates a continuous grid surface from points a natural neighbor technique.</p> <p><b>Trend</b> interpolates a raster surface from points using a trend technique.</p>
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**Advanced Classification** (*Maximum Likelihood, Clustering*):

	<p><b>Multivariate Toolset, Classification tools:</b></p> <p><b>Maximum Likelihood Classification, Iso Cluster Unsupervised Classification</b></p> <p><i>(multiple continuous grid layers)</i></p>	<p><b>Maximum Likelihood Classification</b> performs a maximum likelihood classification on a set of input grid layers (or bands) and creates a classified grid as output. Several tools for creating classification “signatures” are available to include <i>Band Collection Statistics, Create Signatures, Dendrogram, Edit Signatures</i> and <i>Principal Components</i>.</p> <p><b>IsoCluster Unsupervised Classification</b> performs unsupervised classification on a set of input grid layers (or bands) using the IsoCluster classification technique.</p>
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**Predictive Statistics** (*Map Correlation/Regression, Data Mining Engines*):

	<p><b>No direct tools</b></p> <p><i>(two continuous grid layers)</i></p>	<p>The earlier AML Grid set of commands contained tools for <b>CORRELATION</b> (calculates the cross correlation between two input grids and prints the correlation coefficient to the screen) and <b>REGRESSION</b> (outputs the regression coefficients for the regression model in tabular form) were dropped in Spatial Analyst. These statistical operations can be derived using a Python script. Also, the Band Collect tool in the Multivariate toolset provides correlation and covariance summaries.</p>
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**Spatial Analyst** has 170 tools in 22 toolsets for performing spatial analysis and modeling. The above listings identify the analytical tools with traditional math/stat categories in quantitative analysis. The listing below identifies non-analytical support tools (highlighted in grey) involved with specialized applications, raster layer management, conversion, editing, selection, tabular summary or display (housekeeping).

Posted at—

[http://help.arcgis.com/en/arcgisdesktop/10.0/help/index.html#/A\\_complete\\_listing\\_of\\_the\\_Spatial\\_Analyst\\_tools/009z000000wv000000/](http://help.arcgis.com/en/arcgisdesktop/10.0/help/index.html#/A_complete_listing_of_the_Spatial_Analyst_tools/009z000000wv000000/)

**Spatial Analyst toolsets:** (non-analytical tools highlighted in grey)

Toolset	Tools
<a href="#">Conditional</a>	Con • <b>Pick</b> • <b>Set Null</b>
<a href="#">Density</a>	<b>Kernel Density</b> • <b>Line Density</b> • <b>Point Density</b>
<a href="#">Distance</a>	Corridor • Cost Allocation • Cost Back Link • Cost Distance • Cost Path • Euclidean Allocation • Euclidean Direction • Euclidean Distance • Path Distance • Path Distance Allocation • Path Distance Back Link
<a href="#">Extraction</a>	<b>Extract by Attributes</b> • <b>Extract by Circle</b> • <b>Extract by Mask</b> • <b>Extract by Points</b> • <b>Extract by Polygon</b> • <b>Extract by Rectangle</b> • <b>Extract Multi Values to Points</b> • <b>Extract Values to Points</b> • <b>Sample</b>
<a href="#">Generalization</a>	<b>Aggregate</b> • <b>Boundary Clean</b> • <b>Expand</b> • Majority Filter • Nibble • Region Group • <b>Shrink</b> • <b>Thin</b>
<a href="#">Groundwater</a>	<b>Darcy Flow</b> • <b>Darcy Velocity</b> • <b>Particle Track</b> • <b>Porous Puff</b>
<a href="#">Hydrology</a>	Basin • Fill • Flow Accumulation • Flow Direction • Flow Length • Sink • <b>Snap Pour Point</b> • <b>Stream Link</b> • <b>Stream Order</b> • <b>Stream to Feature</b> • Watershed
<a href="#">Interpolation</a>	IDW • Kriging • Natural Neighbor • Spline • Spline with Barriers • <b>Topo to Raster</b> • <b>Topo to Raster by File</b> • Trend
<a href="#">Local</a>	Cell Statistics • Combine • Equal to Frequency • Greater Than Frequency • Highest Position • Less Than Frequency • Lowest Position • Popularity • Rank
<a href="#">Map Algebra</a>	Raster Calculator

<a href="#">Math General</a>	Abs • Divide • Exp • Exp10 • Exp2 • Float • Int • Ln • Log10 • Log2 • Minus • Mod • Negate • Plus • Power • Round Down • Round Up • Square • Square Root • Times
<a href="#">Math Logical</a>	Boolean And • Boolean Not • Boolean Or • Boolean XOr • Combinatorial And • Combinatorial Or • Combinatorial XOr • Diff • Equal To • Greater Than • Greater Than Equal • In List • Is Null • Less Than • Less Than Equal • Not Equal • Over • Test
<a href="#">Math Trigonometric</a>	ACos • ACosH • ASin • ASinH • ATan • ATan2 • ATanH • Cos • CosH • Sin • SinH • Tan • TanH
<a href="#">Math Bitwise</a>	Bitwise And • Bitwise Left Shift • Bitwise Not • Bitwise Or • Bitwise Right Shift • Bitwise XOr
<a href="#">Multivariate</a>	Band Collection Statistics • Class Probability • Create Signatures • Dendrogram • Edit Signatures • Iso Cluster • Iso Cluster Unsupervised Classification • Maximum Likelihood Classification • Principal Components
<a href="#">Neighborhood</a>	Block Statistics • Filter • Focal Flow • Focal Statistics • Line Statistics • Point Statistics
<a href="#">Overlay</a>	Fuzzy Membership • Fuzzy Overlay • Weighted Overlay • Weighted Sum
<a href="#">Raster Creation</a>	Create Constant Raster • Create Normal Raster • Create Random Raster
<a href="#">Reclass</a>	Lookup • Reclass by ASCII File • Reclass by Table • Reclassify • Slice
<a href="#">Solar Radiation</a>	Area Solar Radiation • Points Solar Radiation • Solar Radiation Graphics
<a href="#">Surface</a>	Aspect • Contour • Contour List • Curvature • Cut Fill • Hillshade • Observer Points • Slope • Viewshed
<a href="#">Zonal</a>	Tabulate Area • Zonal Fill • Zonal Geometry • Zonal Geometry as Table • Zonal Statistics • Zonal Statistics as Table